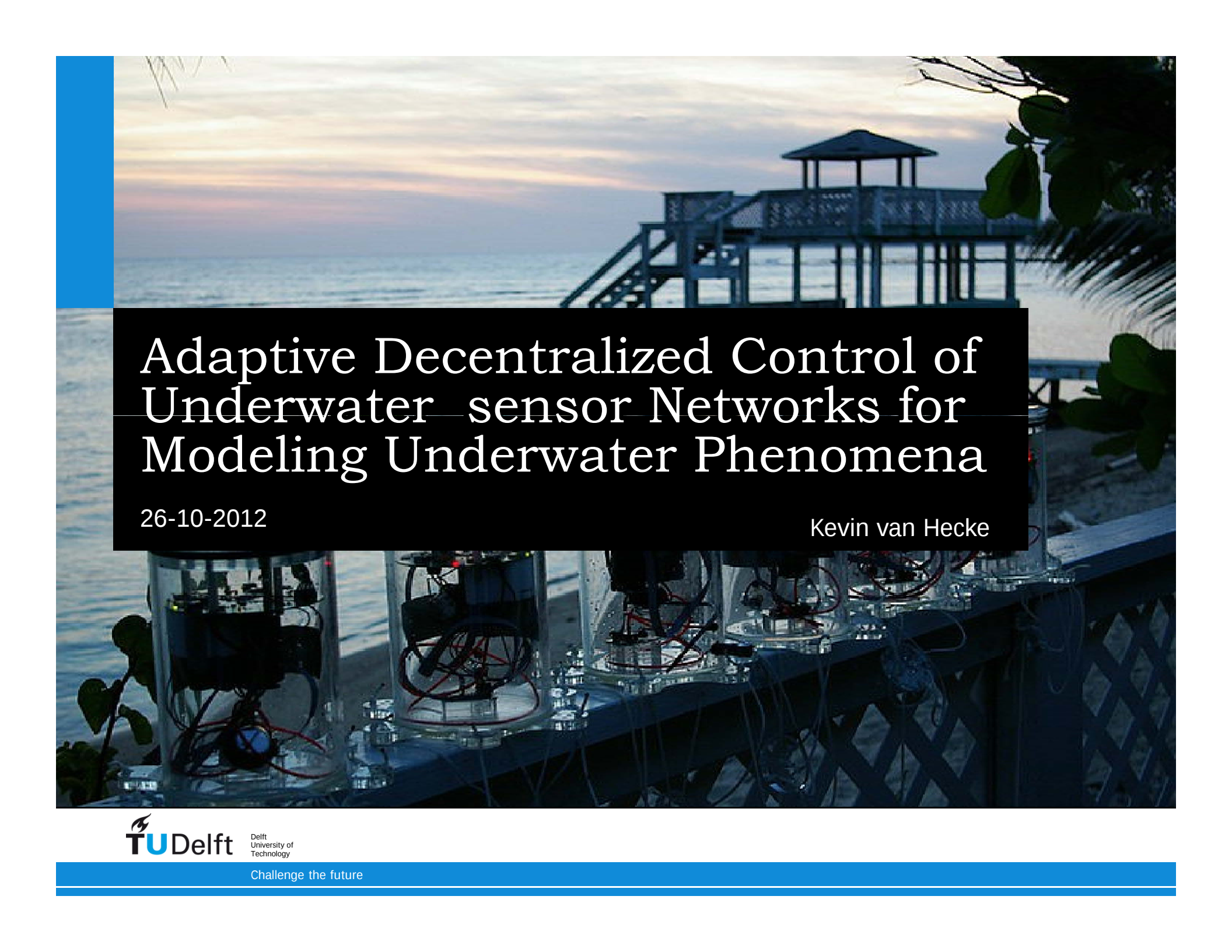




# Adaptive Decentralized Control of Underwater sensor Networks for Modeling Underwater Phenomena

26-10-2012

Kevin van Hecke





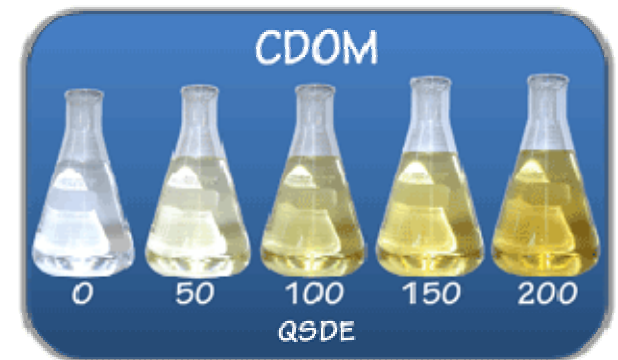
# Contents

- Application background
- Aqua nodes
- Depth adjustment
- Field tests
- Conclusions

# Modeling underwater phenomena

## Background

- Chromophoric Dissolved Organic Matter (CDOM)
  - Remote sensing
  - Estimating light penetration
- Modeling tidal fronts dynamics
  - Measure full volume of the water
  - High density sensors



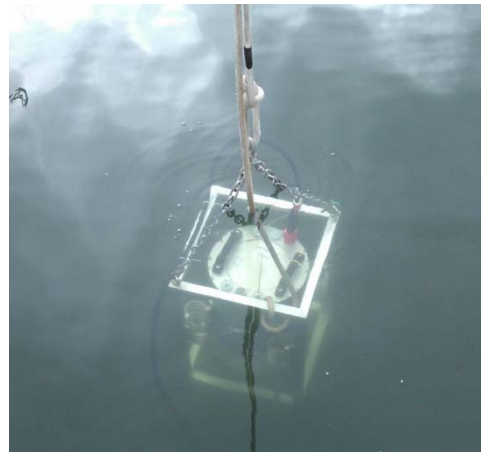
# Modeling underwater phenomena

## Background



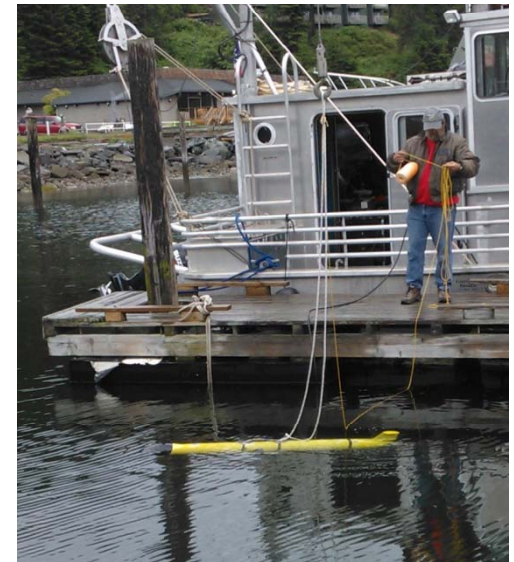
Buoy's

-costs  
-static



Column Profiling

-time  
consuming



ROV's

-costs  
-reliability

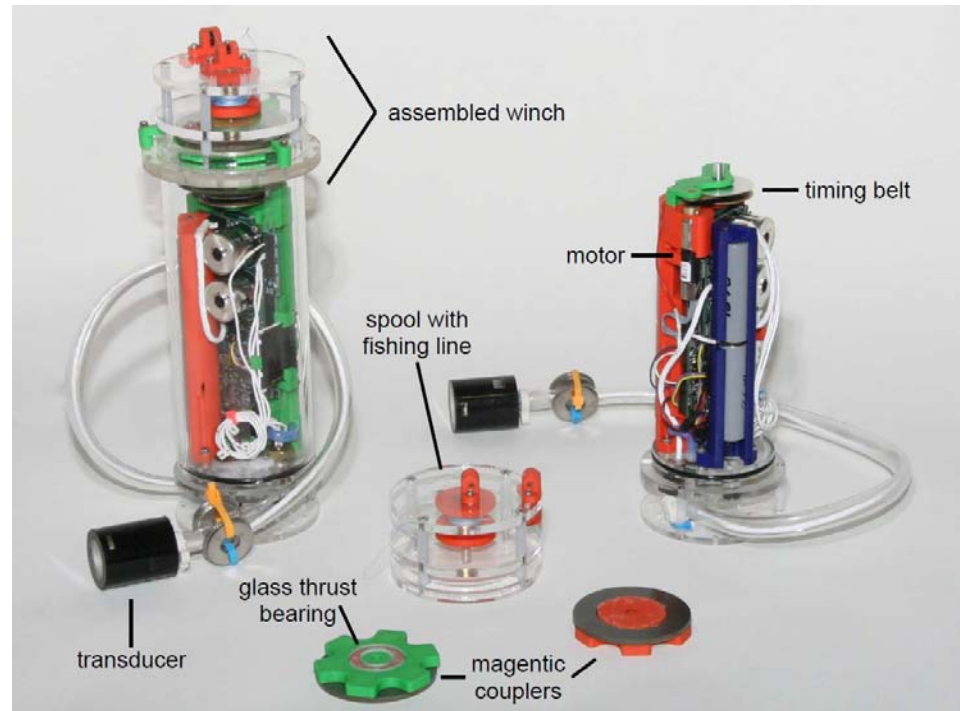
# Aqua node



# Aqua node

## Hardware

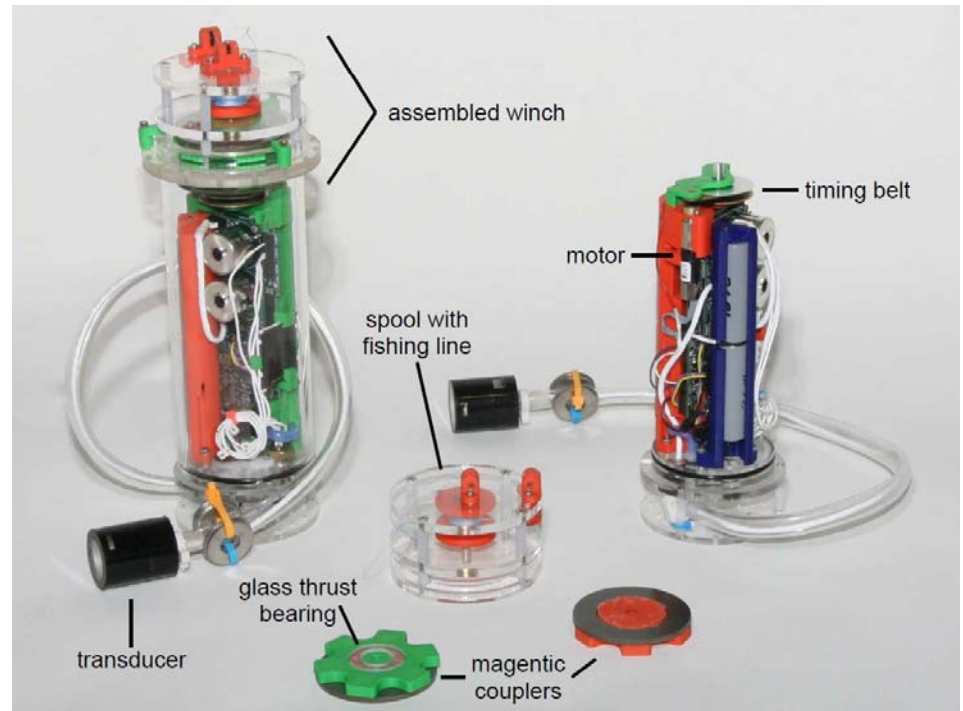
- ARM7TDMI @60MHz
- 40kB of RAM and 512kB flash
- SD-cart
- Sensors:
  - CDOM
  - Pressure
  - Temperature
- Winch depth adjustment system
- Cost: €2000



# Aqua node

## Communication hardware

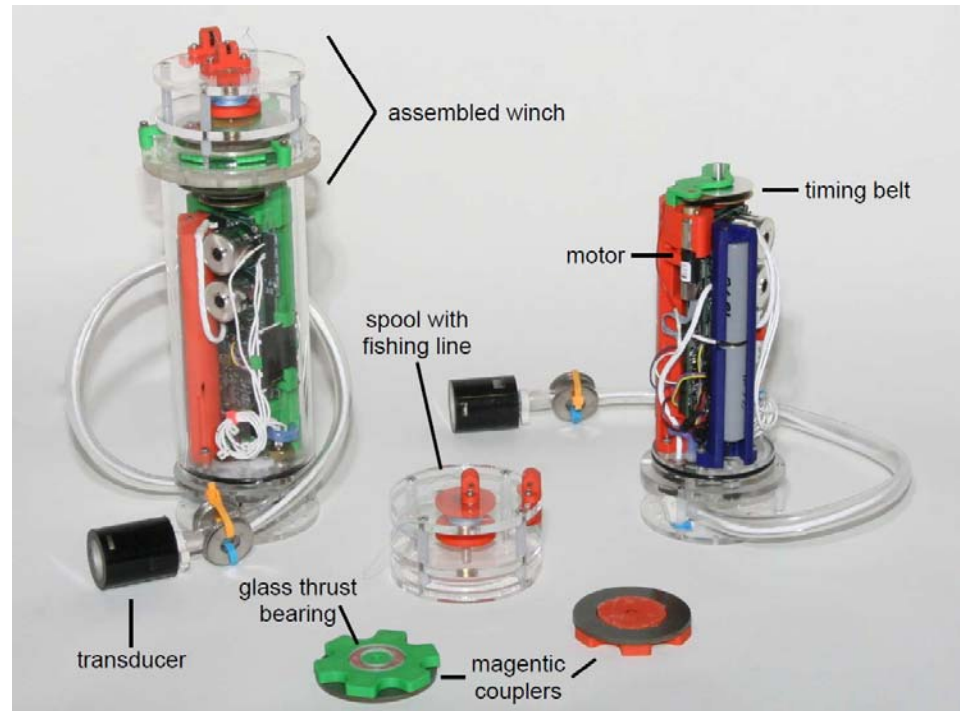
- 10W acoustic modem
  - 300 b/s
  - Self synchronizing TDMA
  - 4 second slots
- Radio communication
  - Only at surface
  - Finding the node



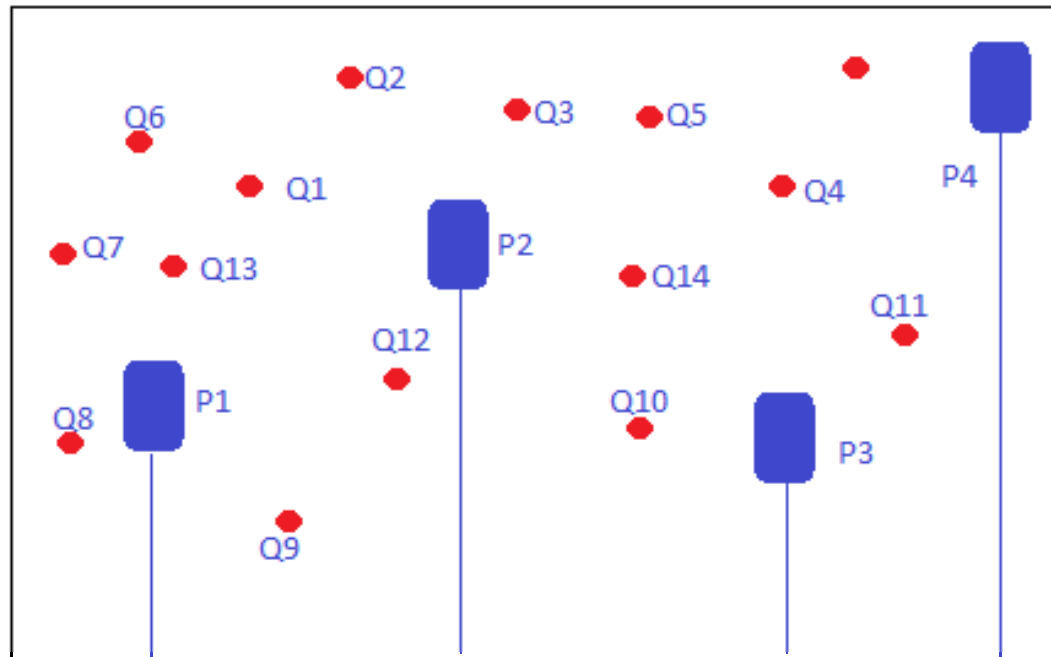
# Aqua node

## Energy

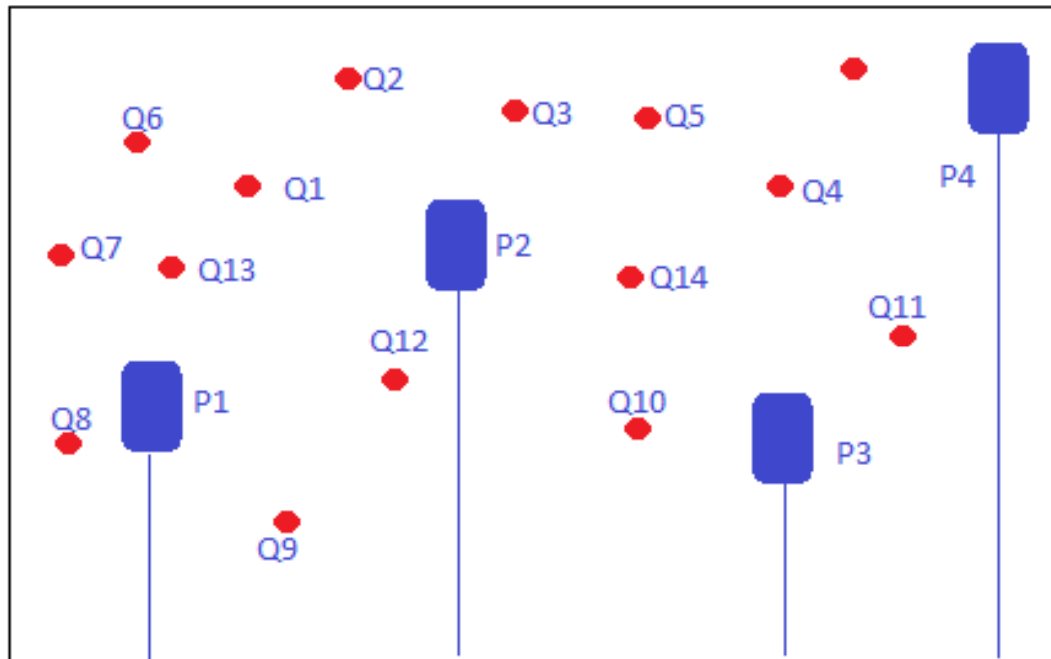
- 60WWhr Lithium Ion
- Sleep mode: one year
- Sensing mode: two weeks
- Depth adjustment: 1W



# Depth adjustment



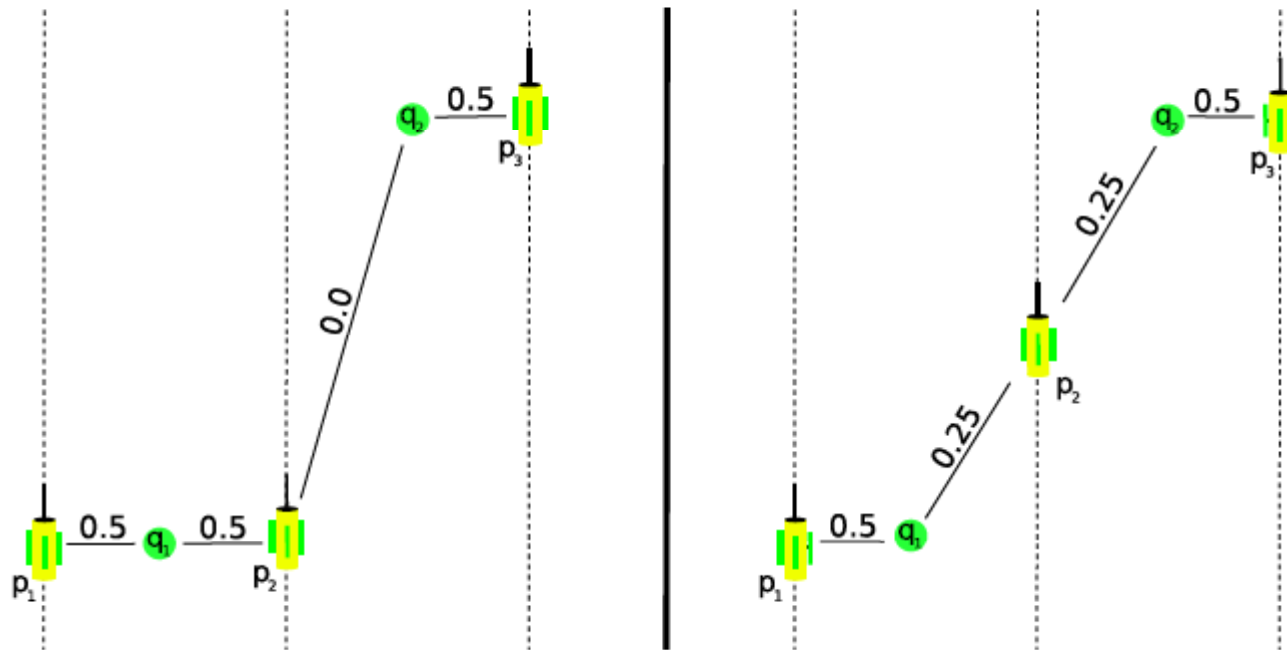
# Depth adjustment



- Maximise:  $Cov(p_1, q_1)$
- For all sensors and all points:

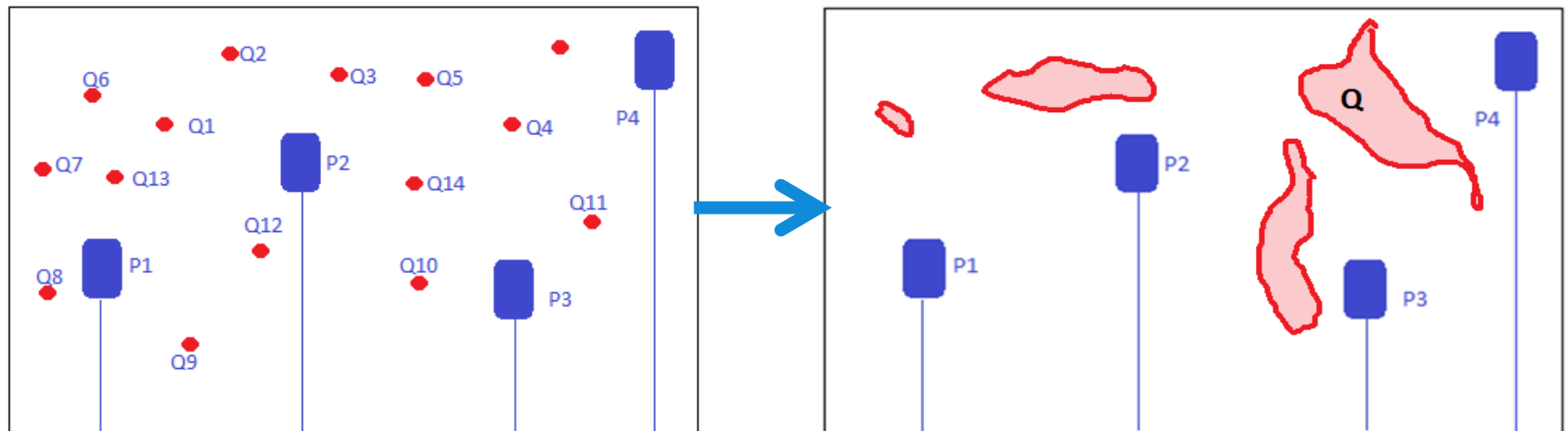
$$\arg \max_{p_i} \sum_{j=1}^M \sum_{i=1}^N Cov(p_i, q_j)$$

# Depth adjustment



$$\arg \max_{p_i} \sum_{j=1}^M \sum_{i=1}^N Cov(p_i, q_j) \quad \rightarrow \quad \arg \max_{p_i} \sum_{j=1}^M \left( \sum_{i=1}^N Cov(p_i, q_j) \right)^{-1}$$

# Depth adjustment



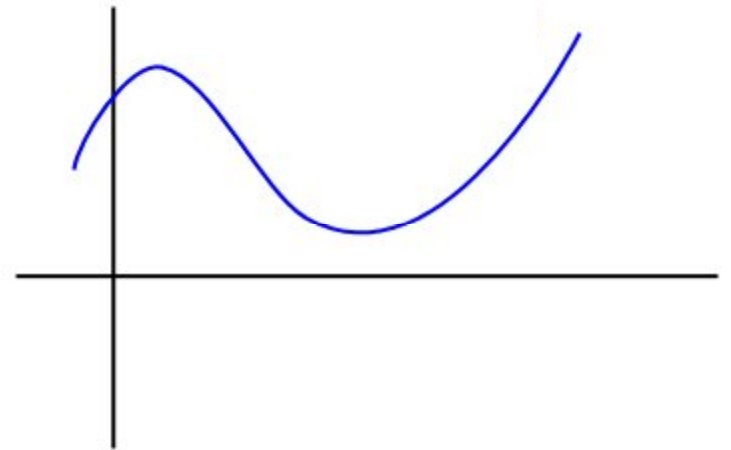
$$\sum_{j=1}^M \left( \sum_{i=1}^N \text{Cov}(p_i, q_j) \right)^{-1} \rightarrow \int_Q \left( \sum_{i=1}^N \text{Cov}(p_i, q) \right)^{-1} dq$$

# Depth adjustment

## The cost function

$$\int_Q \left( \sum_{i=1}^N Cov(p_i, q) \right)^{-1} dq$$

- Optimization problem: find the minimum
- Differentiate with respect to z axis

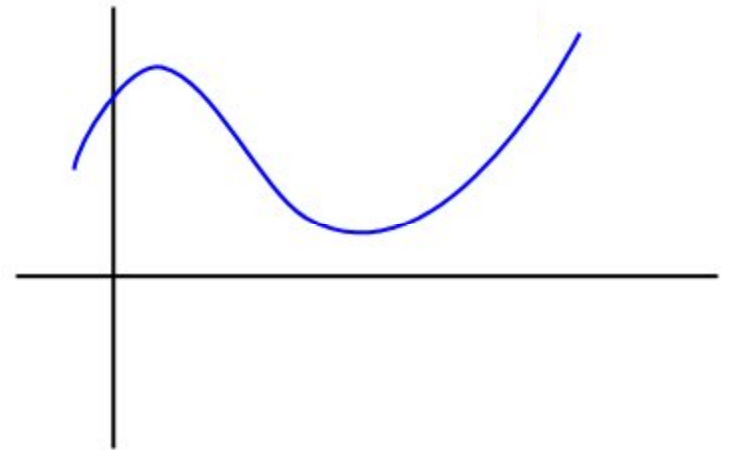


# Depth adjustment

## The cost function

$$\int_Q \left( \sum_{i=1}^N Cov(p_i, q) \right)^{-1} dq$$

- Optimization problem: find the minimum
- Differentiate with respect to z axis



# Test results

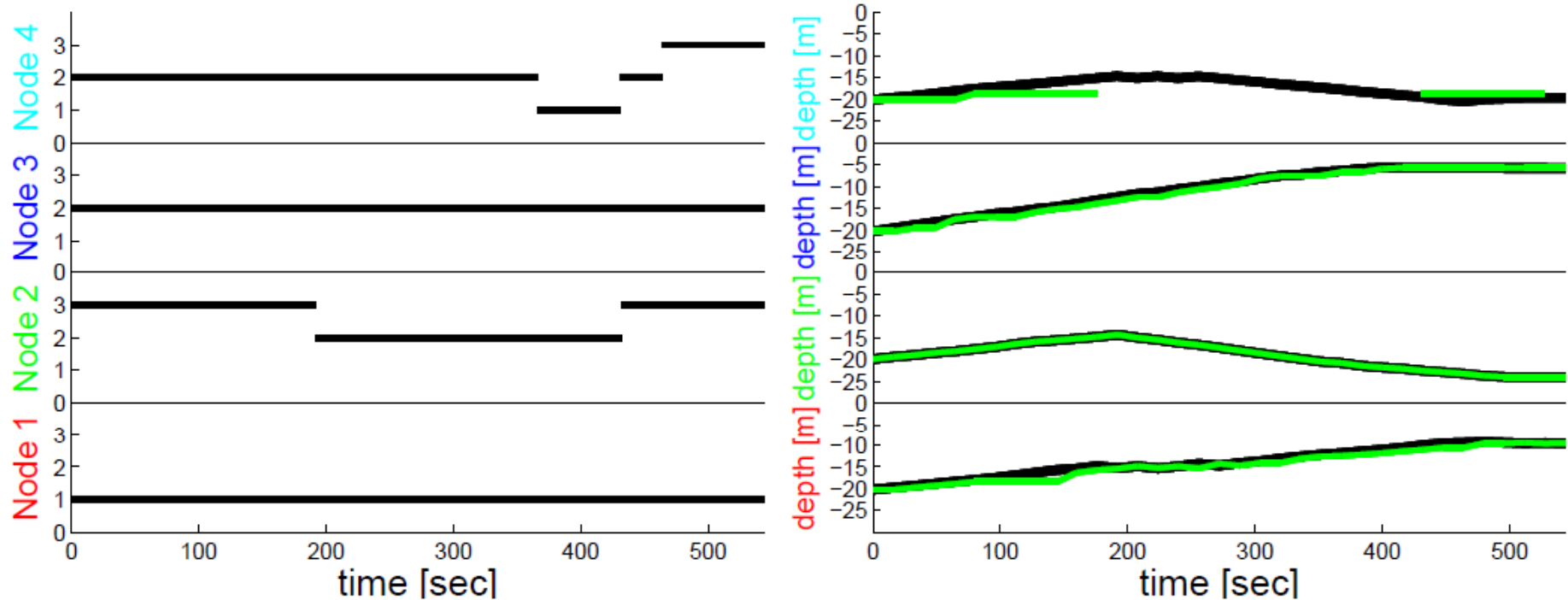
- Matlab simulation
- Pool
- River



# Test results

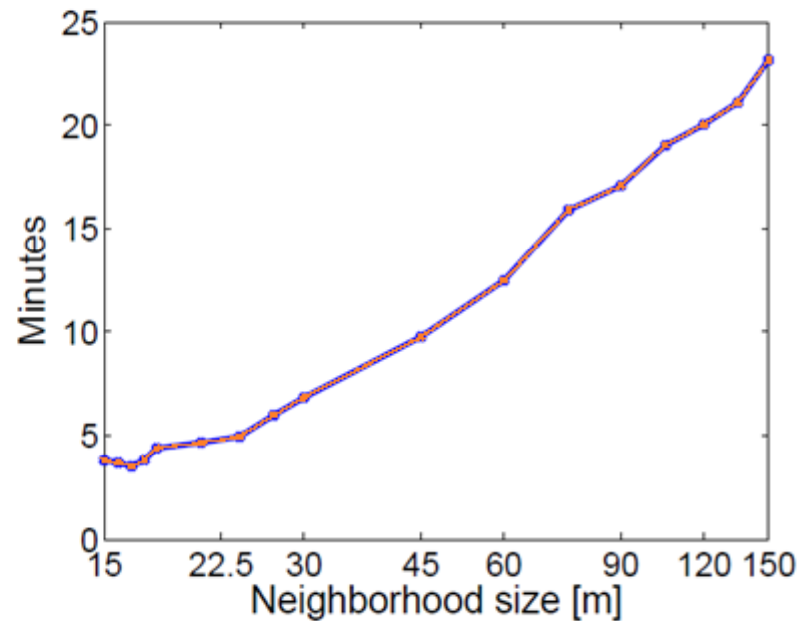
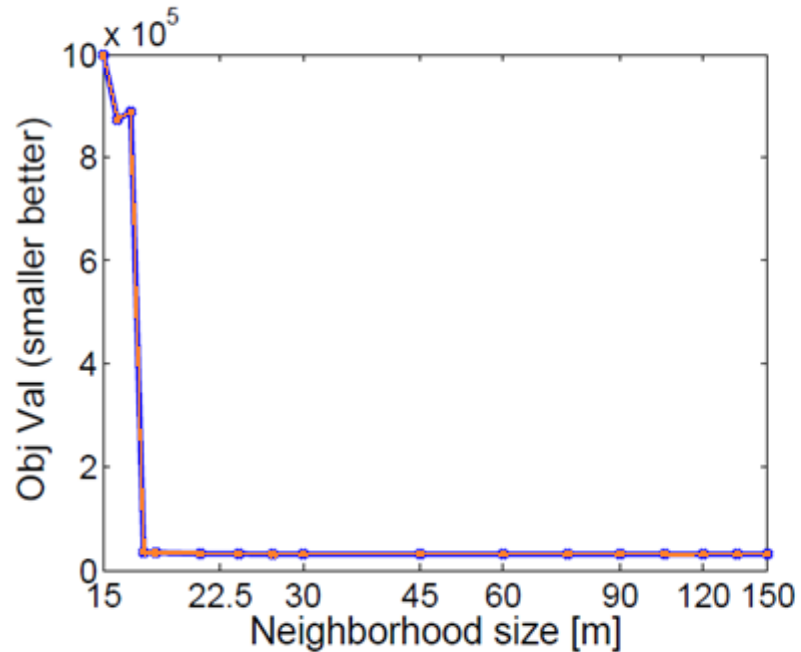
## Number of neighbors

- Each node used information from nodes whose last depth message was received within the past two minutes



# Test results

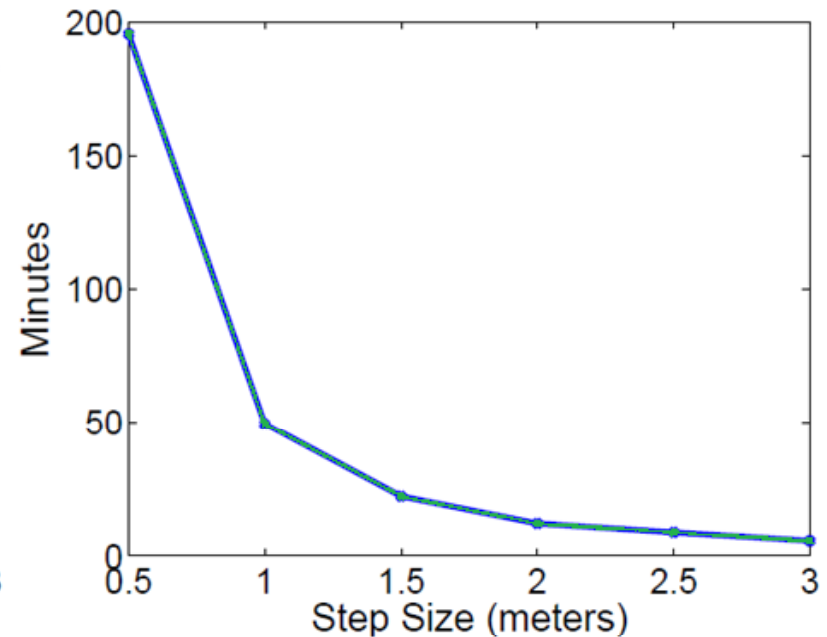
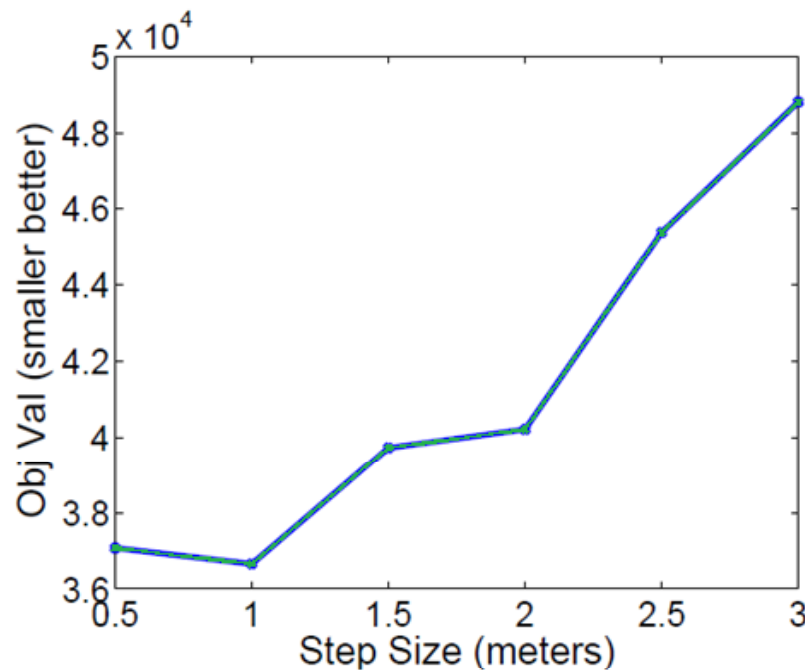
## The Neighborhood size



- Simulation: nodes were placed 15 meters apart
- Nodes only need to hear direct neighbors for good performance

# Test results

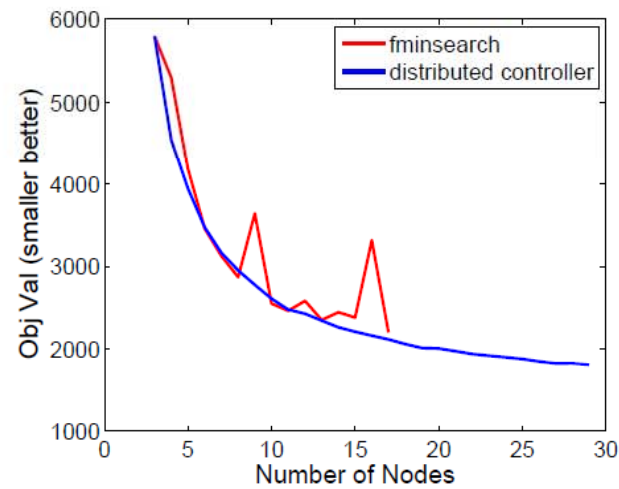
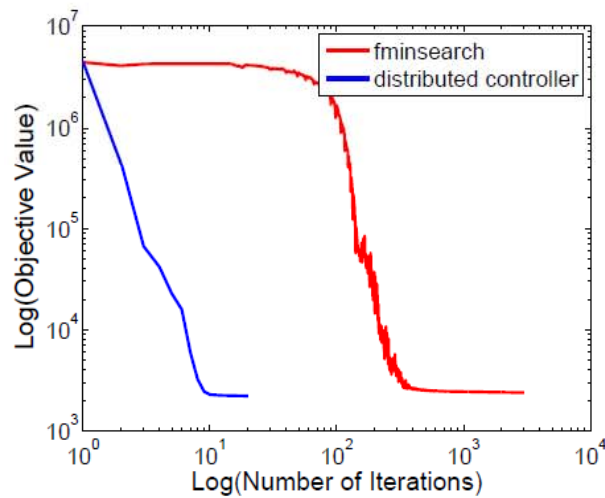
## The grid size



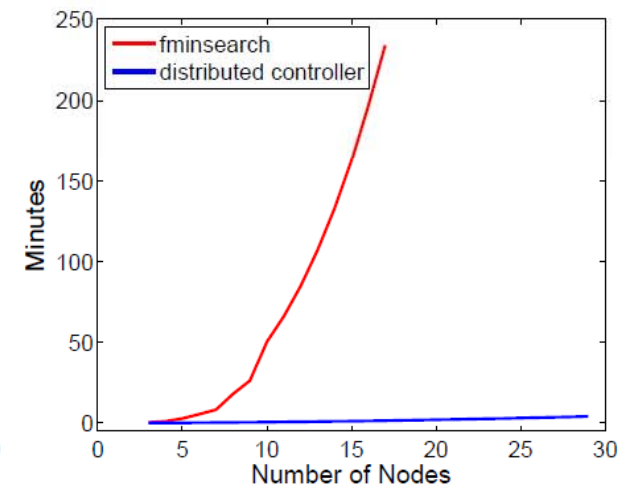
Computation vs. precision

# Test results

## Controller



(a)



(b)

# Conclusions

- Sub marine WSN propose unique challenges
- WSN with depth adjustment enables large volumes analysis of ocean
- Decentralized algorithm to optimize sensor range and communications
- Validated in several field experiments